Application of an interrelated UAS - BIM system for construction progress monitoring, inspection and project management

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ABSTRACT
Construction progress monitoring and constant comparison between “As-planned and the actual state of the project “As-built” is a critical task for construction project managers to keep projects on track. Currently, progress and inspection reports are based on manual input and observation of each and every phase of the construction projects, such processes are costly and time consuming.

Unlike the traditional method for project control, integrating advanced technologies such Building Information Modeling (BIM), Unmanned Autonomous Systems (UAS) and real-time cloud based data modeling and analysis, enable real time project control, monitoring and inspection. Advanced BIM encompasses project As-Planned information such as design, specification, cost, and schedule which enables CPMs to have an accurate comparison between as As-Planned and the UAS based As-Built states of the project. This paper describes:

● The current state for building information modelling and unmanned aerial system in construction projects.
● A strategy for the application and integration of BIM and UAS throughout progress monitoring of the construction of a recreational facility.
● The challenges and opportunities for full automation and data analytics towards real time project control and monitoring of Construction projects.

INTRODUCTION
In the knowledge era and time of Artificial Intelligence (AI) the world is changing much faster than ever before. In a time of disruptive technologies, rapid social, political and environmental changes it is the moral obligation of each and every industry to transform (WEF, 2016). While this transformation will have positive impacts on construction cost, schedule, productivity, efficiency and environmental, the construction industry has remains one of the least efficient industries with an unimpressive track record in the world.

Even though other industry sectors have embraced fundamental changes over the last few decades, and have gained the benefits of advanced technological achievements, process and product innovations, the construction sector has been hesitant to fully embrace the latest technological opportunities, which has thus far resulted in stagnation of productivity in major global construction projects.
Technological advancement and market maturity of digitalization such as 3D scanning and virtual reality, in addition to Building Information Modelling (BIM), Unmanned Aerial and Ground systems (UAS and UGS), autonomous machineries and equipment and advanced building materials has provided a potential for fundamental changes to boost construction sector productivity and efficiency. While new technologies and innovation have emerged to some extent on the enterprise or company level, the rate of innovation and overall productivity in construction sector has remained nearly flat for the last 50 years (Beck, 2016).

According the World Economic Forum report in 2016, the unimpressive record of the construction industry is mainly caused by:

- Lack of innovation and delayed adaptation
- Informal process or insufficient rigour and consistency in process execution
- Insufficient knowledge transfer from project to project
- Weak project monitoring
- Little collaboration with supplier
- Conservative company culture
- Little cross functional cooperation
- Shortage of young talent and people development

Despite all the above mentioned issues and dominant conservative culture in construction sectors, few construction companies have adopted a progressive and innovative approach to pioneer the integration of advanced technologies such as BIM and UAS. This research and its outcomes herein have been the result of a collaborative approach between progressive construction industry partner/owners and academic Scholars/practitioners to: a) study the integration of the advanced BIM UAS based data into the progress reporting, technical inspection and safety analysis of the construction sites, b) demonstrate the advantages of implementing of the integrated strategy and c) identify the technical barrier to advanced technologies such as UAS in the construction sector.

WHAT IS THE STATE OF THE ART?

BIM as an integrated design and construction process is being increasingly incorporated into the construction sector as a tool for advanced design and to provide higher quality, and interactive project plan to improve construction project management (CPM) productivity (Eastman, 2008). The advanced BIM (3D & 4D) and high computerisation level of construction interactive virtual modeling and simulation enabling CPMs to accurately generate project schedule, cost loaded schedule (CLS), and progress reporting plan (Abourizk, 2010). This high level automated process from design to management will impact the overall cost of the project by reducing the number of requests for information (RFI) and change orders. This will results in improved return of investment, Earned Value (EV), and minimize the project cost/schedule contingencies (Barlish & Sullivan, 2012). The integration of BIM in early phases of construction projects also reduce the design conflict, improve communication between project participants, and helps to identify possible, technical, non-technical and managerial issues through the visualization of time- control model (virtual reality) of the project (Arain & Burkle, 2011; Feng et al. 2010).

Even though BIM is mostly being used during the design phase, construction projects would
benefit from the interactive updated BIM model during the implementation phase. To do so
the project progress information has to be captured constantly with the same patterns by the
use of UAS and UGS. Then the captured data has to be integrated into the BIM model and
rendered accordingly to provide the simulation of the future steps based on the As-built data,
planned and Actual value through the construction project (Moeini, 2016; Ghanem &
Abdelrazig, 2006).

Earned Value Management (EVM) as a cost component adds the fifth dimension (5D) to the
BIM system to study and analyze whether the budget and schedule objectives are and will
be preserved before the construction starts and during each phases of project. The
implementation of effective and efficient EVM through BIM also requires constant update of
the project data extradited from the advanced project progress reports. However, obtaining
true values for tasks’ completion rate is difficult (Fleming & Koppelman, 1997) and requires
advanced situational and progress reporting and up-to-date information regarding as-built
state which has to be attained frequently and compared to the as-planned state. Hence
integration of new data acquisition methods and modeling techniques such as UAS, UGS,
remote sensing and AI rather than traditional methods (Arian & Moeini, 2016) is necessary.

Application of UAS, UGS, and remote sensing enables the CPMs to go beyond the labour-
and time intensive traditional process of As-built reporting which is usually based on 2D
plans. The collected As-built information acquired by High Definition (HD) cameras, laser
scanning and photogrammetric point clouds as a modern approach can be used to provide
the necessary information for As-built demonstration in the BIM (Ham et al., 2016; Maalek, et
al., 2015; (Karsch et al., 2014; Golparvar-Fard et al., 2012).

UAS autonomous flight planning capability enable the CPM to predefined mission planning
(knows flight pass in UAS) through the project and took the required measurements for
collision avoidance during each pre-planned flight. The work of Freimuth and König (2015)
explained the automated calculation of the UAS mission planning using a BIM by defining
the secure distance to all objects during the operation of the autonomous systems to: a)
improve the safety of the operation, and b) plan the UAS operation based on the latest up-
dated BIM.

The work of Tuttas et al (2015) illustrates the photogrammetric point clouds which are
generate based on the captured data by UAS through the projects was used used for the
project progress monitoring (As-built) as well as detection of temporary objects (e.g. cranes)
for future mission planning of the UAS. Integration of As-built information (captured by UAS
and UGS) into the BIM enabled the CPM to: make well-informed decision, enhanced
communication management, and ultimately improved the project success and productivity
rate (Arain & Moeini 2016).

INTEGRATED BIM – UAS SYSTEM

The integrated BIM-UAS system is a “big data” collection with data analytical capacity. The
strategy behind integrating building information modelling and unmanned aerial systems
aims to firstly primarily build the capacity for real time automated visualization of project
progress. Before developing an integrated BIM-UAS system, it is necessary to identify
separately how the building information modeling and the UAS (drones) can be strategized
separately within construction projects.

For those construction projects that incorporate BIM as part of the design and planning phase, the 3D building information model provides data and information of the ‘As-planned or As-designed” project. The BIM model as part of the integrated design process enables the creation of the 3D model benchmark information data as illustrated below.

![Figure 1. The building information modeling data generation](image1)

In the implementation of unmanned aerial systems for monitoring, the drones are used to capture data of the construction progress. In this context, the project site is scanned by the use of UAS at a predetermined frequency (monthly or semi-monthly) for the duration of the construction. The frequency can thus be directed on the basis of the project control requirement. The collected data is then processed before data analytics derive a cloud model representative of the “As-built” model, illustrated below.

![Figure 2. The cloud point generation using unmanned aerial systems](image2)

Lastly, the integrated BIM-UAS process is the ultimate post processing of input data from: a) the BIM model, and b) the cloud model post processed from the drone input information.

The framework for an integrated BIM-UAS process as shown below, allows for the integration of site-wide survey-grade imagery, which are overlaid with BIM design data.

The integrated BIM-UAS model serves for project control by comparing the As-built” and “As-designed model. Algorithms and further data processing of the integrated model should allow the generation of project control metrics and KPIs such as earned value or cost variance.
TESTING THE UAS BIM SYSTEM

Unmanned Aerial and Ground Systems which provide the capability of low altitude aerial photogrammetry and ground based imagery can provide a unique advantage to improve the project progress reporting and quality in construction sites. The UAV and UGV technology has become the center of attention of some construction companies and expands the practical application scope. The capability of the UAS to capture low altitude aerial (airborne) photogrammetry on urban project site and the suitability of the captured images to make 3D model of project progress has made UAVs one of the most influential tools for construction project management.

Three dimensional simulation of the project site in addition to the virtual reality resulted from the overlapping of the As-planned and As-built data enable the research team to visually analyse the project progress during the implementation phase.

In order to validate the implementation of UAS in construction project monitoring, testing was conducted on a selected project. The project is a recreation facility located within the inner city of Calgary (Alberta, Canada). The site is tucked between an existing hill landscape and highest natural elevation and a reconstructed wetland.

Figure 4. The Rocky Ridge Facility in Calgary (The City of Calgary)
The project site is approximately 284,000 square feet building, designed to complement the surrounding landscape. The roof component of the structure is quite unique making it the largest wooden glulam supported roof in North America. The highway and residential neighborhood located in the southern part of the project site was one of the main risks associated with safe operation of UAS. The UAS operation was the first official and legal UAS flight with the city boundary under Special Flight Operation Certificate (SFOC) issued by Transport Canada.

The construction site was monitored by the use of UAS and the required photogrammetric data was captured since very early stage of the project on every three weeks bases. The captured combining nadir and oblique airborne (UAS) images of the project site were used to generate a georeferenced 3D cloud point and orthomosaic for further analysis.

The UAS acquisition is associated to an acquisition with several UAS platforms mainly DJI products and adherence to the regulation for UAS flights in Canada, which are among others:

- Maximal flight height of 400 Feet
- Flight was conducted within visual line of sight
- No flights was conducted over the main highway on the southern part of the site
- No flights was conducted during working hours
- No flight was conducted below -5 degree centigrade

A monthly frequency of site monitoring was implemented throughout the two year duration of the project. For executing each monthly flight in the project site the DJI Flight Planner and DJI mission planner apps were used. At beginning of the project the Industry Foundation Classes (IFC) process was used to avoid obstacle as explained by Freimuth and König (2015). Obstacle avoidance sensors were later integrated into the UAS platforms which enabled the team to move beyond the Industry IFC limitation and lengthy process of mission planning to avoid obstacles. The adoption of avoidance sensors into the drone system has reduced the UAS flight planning based on obstacle avoidance, data capturing time and also improve the flight operational safety.

The geometries of the building and site layout elements, which lay in the neighborhood of the take-off and surveying position, were extracted as bounding boxes. Using the bounding boxes and the data of the surveying job, grid points were generated. These grid points were the main basis to calculate the optimal waypoint between the take-off and surveying position. The results were stored as flight mission and were be evaluated by simulating the flight of the UAS in an interactive viewer component of the Survey Planner application.

The wide angle cameras used in UAS increased the base-height ratio (distance on the ground between the centers of overlapping photos, divided by aircraft altitude) and improved the accuracy of height measurement with the wide angle of view from the longitudinal direction. The lateral direction increased the surface width covered in the captured images and improved the efficiency of the flight. It also reduced the quantity of the control points in the project site (Feifeia et al, 2012). The image below is an illustration of the As-built images acquired during a flight over the construction site.
The Pix4D a photogrammetry software was used to generate 3D point cloud model from the captured photos. The geolocation and camera orientation of each picture and camera specifications was used to calibrate the photos inside the software. The image below shows the calibrated camera positions in green and the initial camera positions (GPS coordinates) in blue. Depending on the number of images used the time to generate the 3D point cloud model varies. On average it took 48 to 72 hours to generate a model as shown in the images below.

Finally, the as-built Point Cloud model was manually overlaid over the BIM Model using Autodesk Naviswork, a 5D BIM simulation and analysis software. The point cloud and BIM models were compared visually. The latter visual matching between the As-built and As-planned models is currently the last step of data processing visualisation to allow a benchmark comparison between project up to date status and initial planned data.

**OPPORTUNITIES AND CURRENT LIMITATIONS**

Cost overruns and delays occur in construction projects often when the realities of the physical world are out of alignment with the plans of the digital world. The BIM-UAS integrated model and system bridges the gap between the project planned features and the completed project features. The integration of site-wide survey-grade imagery, perfectly overlaid with BIM design data is so far the closest project control and monitoring could get to enable real time visualization of progress.
The proof of concept for the integrated BIM-UAS system was successfully demonstrated with the recreational facility construction project. Indeed, photogrammetry can be used to generate a relatively accurate 3D Cloud Point Models that can be used over existing 3D design models to enable construction progress monitoring.

The data analysis and processing of the terabytes of collected data in various forms, although lengthy has provided accurate comparison between the point cloud models and the BIM 3D model. The benefits and opportunities have been well demonstrated within the framework of the selected project

Limitations however persist as the data generated is currently qualitative with a visualization of the project progress. For the purpose of validating the BIM-UAS model, in absence of any software capable of aligning the BIM model and the point cloud model, the integration followed a manual step by step process of data processing and post processing. Notably, the next step would consist in automating the data analytics to produce quantitative and measurable data for project control and performance monitoring.

In order to optimize the BIM-UAS integrated system for project monitoring and inspection, the next development steps have to target:

- achieving an automation of the integrated BIM-UAS system to generate a real time visual of the 3D geometries over the UAS scanned model.
- a real time data processing that extracts the key project control metrics to enable project managers with the capacity to reduce risks while increasing project productivity. Linking schedule BIM model (4D) and adding project cost BIM (5D), should enable that functionality.

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